

2-dimensional, measuring range up to $\pm 90^{\circ}$ CANopen® / SAE J1939

Overview

- Designed for Mobile Maschines
- E1 compliant design
- Load dump protection
- Protection up to IP 69K
- Corrosion protection CX (C5-M)
- Connection cable / cable with M12 connector
- Interface CANopen® / SAE J1939
- Redundant versions (2-channel architecture)
- Applicable up to PLd (ISO 13849)



Picture similar

Technical data				
Technical data - electrical r	ratings	Technical data - electrical ratings		
Voltage supply	836 VDC	Interference immunity	EN 61000-6-2	
Reverse polarity protection	Yes		ISO 7637-2*	
Short-circuit proof	Yes		ISO 7637-3* ISO 11452-2*	
Consumption typ.	15 mA (24 VDC, w/o load) 30 mA (24 VDC, w/o load, redundant)		ISO 11452-2 ISO 11452-4* ISO 11452-5*	
Initializing time typ.	≤ 1 s after power on		EN 61000-4-2 (CD ±8 kV, AD ±15 kV)	
Interface	CANopen® SAE J1939		* Severity level according to ECE R10 (Rev. 6 + Amd 02:2021-12)	
Measuring range	±90°	Emitted interference	EN 61000-6-3	
Resolution	1 0.001 ° CANopen® 0.01 ° SAE J1939		EN 61000-6-4 ISO 7637-2* CISPR 25:2008 (301000 MHz)	
Accuracy (+25 °C)	Typ. ±0.1°		* Severity level according to ECE R10	
Repeatability typ.	0.025 ° (+25 °C)		(Rev. 6 + Amd 02:2021-12)	
Absolute accuracy max. (horizontal)	$\pm 0.24^{\circ}$ (+25 °C) $\pm 0.41^{\circ}$ (0+50 °C) (measuring range $\pm 10^{\circ}$, see general information)	MTTF _d (ISO 13849)	High (>100 years) Use in safety functions exclusively based on quick start guide, Application Note and MTTFd reliability prediction (request sep-	
"Absolute accuracy max. (vertical)	$\pm 0.47^{\circ}$ (+25 °C) $\pm 0.86^{\circ}$ (0+50 °C) (measuring range $\pm 10^{\circ}$, see general information)	Programmable parameters	arately). Preset / zero position Resolution Limit frequency (low-pass filter)	
Cross-axis-sensitivity max.	±0.23° (2-dimensional horizontal)		Rotating direction	
(+25 °C)	±0.47° (2-dimensional vertical) Measuring range ±10°	Diagnostic function	Supply voltage monitoring Temperature control	
Sensing method	MEMS technology	Approval	UL approval / E217823	
Sensing rate	1000 Hz (1 ms)	Technical data - mechanica	al design	
Limit frequency	0.130 Hz, 2. order / low-pass filter	Dimensions W x H x L	72 x 24 x 64 mm	
Output stages	CAN-Bus compatible ISO 11898	Protection EN 60529	IP 66	
Load dump protection	ISO 16750-2 for 12 V/24 V systems Pulse 5b (test criteria B)		IP 67 IP 68 (without connector) IP 69K (without connector)	
		Material	Housing: polyamide (glass fiber reinforced) Base plate: metal	

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Technical data						
Technical data - mechanic	al design	Technical data - mechanical design				
Corrosion protection	IEC 60068-2-52 Salt mist	Temperature changes	EN 60068-2-14, -40+85 °C			
	for ambient conditions CX (C5-M) accord-	Weight approx.	150 g			
	ing to ISO 12944-2	Connection	Flylead connector M12, 5-pin, length 300			
Operating temperature	-40+85 °C (see general information)		mm			
Resistance	EN 60068-2-6 Vibration 30 g, 60-2000 Hz EN 60068-2-27 Shock 200 g, 3 ms EN 60068-2-64 Random vibration 10 grms, 20-1000 Hz					

Optional

- 3-axis acceleration PDO mappable (see general information)
- GIM140R-compatible SDO baud rate table
- With integrated terminating resistor

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General information

For a precise thermal design, the self-heating of the inclination sensor must be taken into account depending on the mounting and ambient conditions as well as the electronics and supply voltage. As an approximation, 5 K self-heating applies when the sensor is mounted on a painted metal base. If the inclination sensor is operated close to the maximum characteristic values, the actual temperature at the housing of the inclination sensor must be measured. The specified transverse sensitivity applies to reference mounting. Electromagnetic influences can lead to reduced measuring accuracy (see application note). Reference the zero position of the inclination sensor after installation. Regularly check the zero point stability of the inclination sensor when installed. Acceleration values (optional) are for information purposes only. Further information on request.

Installation position



Horizontal installation

When installing the 2-dimensional inclination sensor with the housing in horizontal position, make sure the base plate is aligned parallel to the horizontal line.

The X and Y axes of the sensor can each be inclined relative to the horizontal plane, which corresponds to a rotation about the other axis. There is one measured value supplied for each axis. Sensor default is 2-dimensional measuring within the selected range, e.g. ±30°. Zero-crossing is exactly in the horizontal line

Inclination angle 0° X-axis, Slope long



Inclination angle +30° X-axis, Slope long



Inclination angle 0° Y-axis, Slope lateral



Inclination angle -30° Y-axis, Slope lateral





Vertical installation

When installing the 2-dimensional inclination sensor with the housing in vertical position, make sure the base plate is aligned parallel to the vertical line. The X and Y axes of the sensor can each be inclined relative to the horizontal plane, which corresponds to a rotation about the other axis. There is one measured value supplied for each axis.

Sensor default is 2-dimensional measuring within the selected range, e.g. ±30°. Zero-crossing is exactly in the vertical line.

Inclination angle 0° X-axis, Slope long



Inclination angle +30° X-axis, Slope long



Inclination angle 0° Z-axis, Slope lateral



Inclination angle +30° Z-axis, Slope lateral



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Terminal	assignment	
Cable with	n connector M	12, 5-pin
Pin	Assignment	Description
1	CAN_GND	Ground connection relating to CAN
2	+Vs	Voltage supply
3	GND	Ground connection relating to +Vs
4	CAN_H	CAN Bus Signal (dominant High)
5	CAN_L	CAN Bus Signal (dominant Low)
4 4	2	M12 flange connector (male), A-coded
M12-1		

Cable with connector 2xM12, 5-pin (Bus-in/Bus-out)

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Pin	Assignment	Description
1	CAN_GND	Ground connection relating to CAN
2	+Vs	Voltage supply
3	GND	Ground connection relating to +Vs
4	CAN_H	CAN Bus Signal (dominant High)
5	CAN_L	CAN Bus Signal (dominant Low)
5 3	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	M12 flange connector (male / female), A-coded
M12-1	M12-2	

Cable with connector 2xM12, 5-pin (2x Bus-in)

Pin	Assignment	Description
1	CAN_GND	Ground connection relating to CAN
2	+Vs	Voltage supply
3	GND	Ground connection relating to +Vs
4	CAN_H	CAN Bus Signal (dominant High)
5	CAN_L	CAN Bus Signal (dominant Low)
5 3 4 • • • • 2	2 4 0 0 2	M12 flange connector (male), A-coded

For all connection types

M12-2

M12-1

Terminals GND and CAN_GND are internally connected and identical in their functions. Max. load on the terminals Vs and GND is 1.5 A each. Daisy chain current max. 1.5 A.



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CANopen® features	
Device profile	CANopen® CiA DS 301 V4.2 Inclinometer profile DS 410 V2.0 LSS service profile DS 305 V3.0
Default	Resolution 0.1° Limit frequency 5 Hz Baud rate 250 kbit/s Node-ID 1 Node-ID 2 (redundant version) Time-driven: 100 ms

SAE J1939 features

Default

Resolution 0.01° Limit frequency 5 Hz Transmission rate 250 kbit/s Address: 247, 248 (redundant version)

Data transfer	
CANopen - PDO Mapping / Node-ID 1 / PDO 1	

LSB	MSB	LSB	MSB	LSB	MSB	
Byte 0	1	2	3	4	5	
Temperatui	re	Inclination a X-axis Slope long in steps of Increasing clockwise r	= 0 ▶±90° 0.1° angle with	Inclination angle Y-/Z-axis Slope lateral = 0 ▶±90 in steps of 0.1° Increasing angle with clockwise rotation		

CANopen - PDO Mapping / Node-ID 2 / PDO 1

LSB	MSB	LSB	MSB	LSB	MSB
Byte 0	1	2	3	4	5
Temperatui	re	Inclination X-axis Slope long in steps of Increasing clockwise r	= 0 ▶±90° 0.1° angle with	Inclination Y-/Z-axis Slope latera in steps of Increasing clockwise r	ll = 0 ▶±90° 0.1° angle with

SAE J1939 - PGN 65363: 2-dimensional device message

LSB	MSB	LSB	MSB	LSB	MSB	LSB	MSB
Byte 1	2	3	4	5	6	7	8
X-axis signed v reading (resoluti 0.01°)		Y-/Z-axis signed v reading (resoluti 0.01°)	vord tilt	Temp. signed byte (°C)	Modul e ID	Error ID	

Data length: 8 bytes Extended data page: 0 Data page: 0

PF: 255 (Prop. B)

PS: 83 Priority: 6

PG number: 65363 (00FF53h)

Description of data payload:

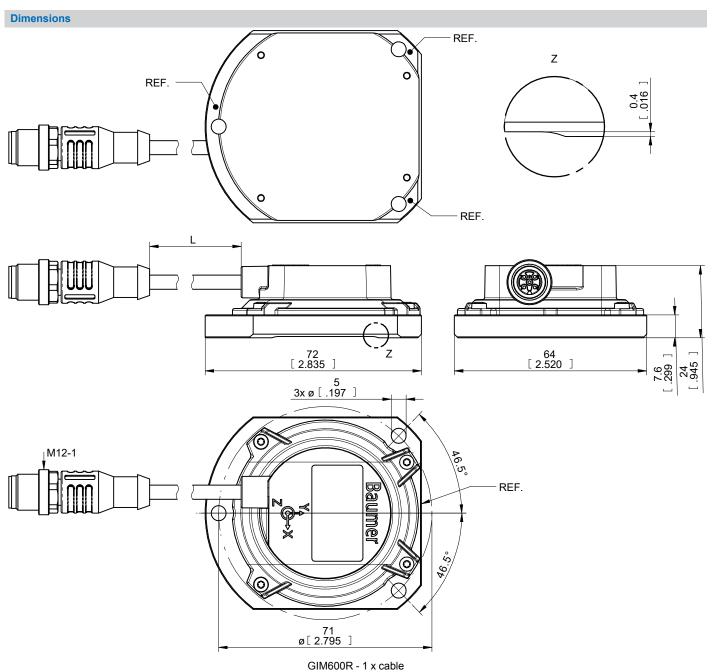
Byte 1: X-axis signed word LSB tilt reading (resolution 0.01°)
Byte 2: X-axis signed word MSB tilt reading (resolution 0.01°)
Byte 3: Y-/Z-axis signed word LSB tilt reading (resolution 0.01°)
Byte 4: Y-/Z-axis signed word MSB tilt reading (resolution 0.01°)

Byte 5: Device temperature signed byte (resolution 1 °C)

Byte 6: Module ID Byte 7,8: Error ID

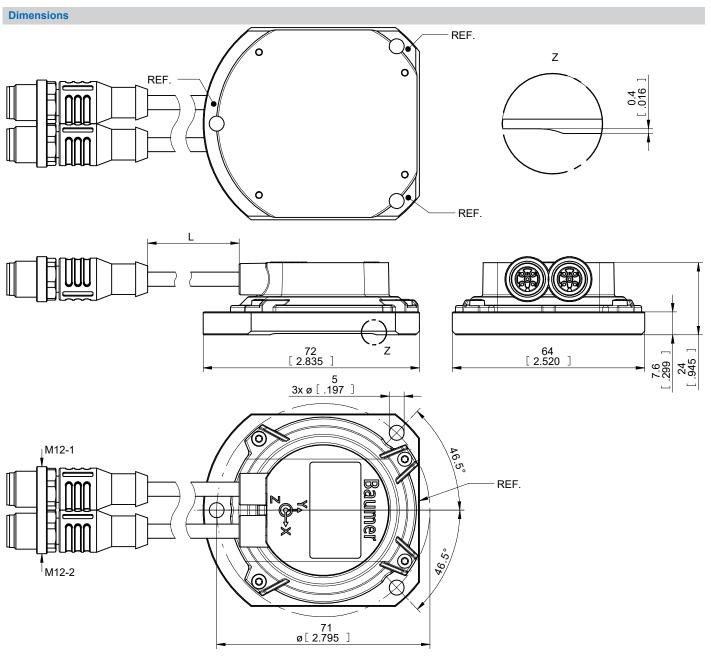


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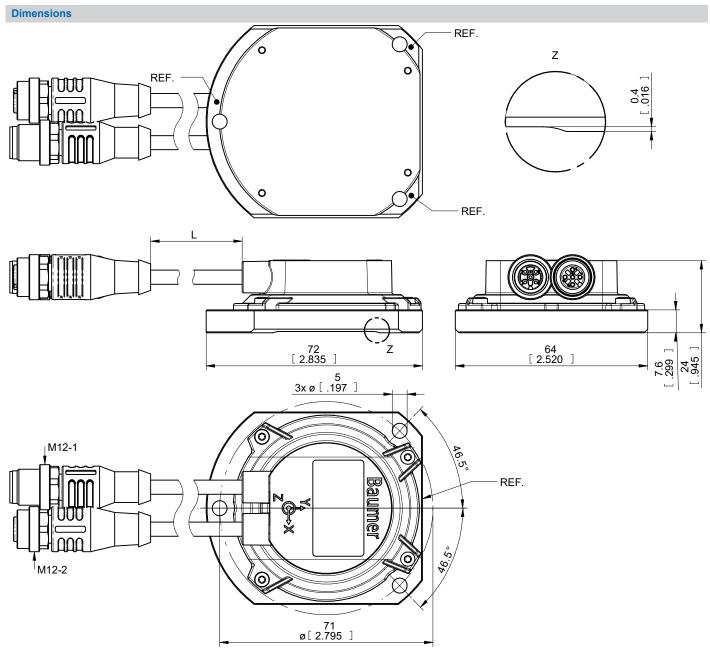


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GIM600R - 2 x cable (male and female contacts)

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Dimensions 35 35 A-A [1.37795] >10 [0.3937] Α 3x M4 ⊕ Ø0.2 A B 80 [3.14961] [2.79528] (7.56) [0.29764] (7.56) [0.29764] +0.2 32 .25984] ____0.2_A В (25.75) [1.01378] (25.75) [1.01378] >7.6 [0.29921] 46.50 46.5°

GIM600R - Drilling pattern / mounting plate



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Ordering reference									
	GIM600R	- N	#	90	. #	##	٠.	Α	1
Product									
	GIM600R								
Housing									
Plastic reinforced / base plate metal		N							
Number of axes									
2-dimensional, housing horizontal			2						
2-dimensional, housing vertical ⁽²⁾			٧						
Measuring range									
±90°				90					
Connection ⁽¹⁾									
Cable 0.3 m with M12, 5-pin, male contacts					5	3			
2x cable 0.3 m with M12, 5-pin, male and female contacts (Bus-in/out)					F)			
2x cable 0.3 m with M12, 5-pin, 2x male contacts (2x Bus-in)					F	?			
Voltage supply / interface									
836 VDC / CANopen® (1-channel)						C6	6		
836 VDC / CANopen® redundant (2-channel design)						C	3		
836 VDC / SAE J1939 (1-channel)						C)		
836 VDC / SAE J1939 redundant (2-channel design)						CF	2		
Operating temperature									
-40+85 °C								Α	
Ontion									

Option

Without option

- (1) Other connection types on request
- (2) On request