

2-dimensional, measuring range up to ±90° CANopen® / SAE J1939

Preliminary

Overview

- Designed for mobile machines
- E1 compliant designLoad dump protection
- Protection up to IP 69K
- Corrosion protection CX (C5-M)
- Connection cable / cable with M12 connector
- Interface CANopen® / SAE J1939
- Redundant versions (2-channel architecture)
- Applicable up to PLd (ISO 13849)



Picture similar

| Technical data | | | |
|-------------------------------------|---|-------------------------------|--|
| Technical data - electrical r | ratings | Technical data - electrical r | ratings |
| Voltage supply | 836 VDC | Interference immunity | EN 61000-6-2 |
| Reverse polarity protection | Yes | | ISO 7637-2* |
| Short-circuit proof | Yes (28 VDC or ground) | | ISO 7637-3* ISO 11452-2* |
| Consumption typ. | 30 mA (24 VDC, w/o load) 60 mA (24 VDC, w/o load, redundant) | | ISO 11452-2* ISO 11452-4* ISO 11452-5* |
| Initializing time typ. | ≤ 1 s after power on | | ISO 10605:2008 + Amd 1:2014 (CD ±8 |
| Interface | CANopen® SAE J1939 | | kV / AD ±15 kV) * Severity level according to ECE R10 |
| Measuring range | ±90° | E ''' 1' ' ' ' | (Rev. 6 + Amd 02:2021-12) |
| Resolution | ≥ 0.001 ° CANopen® 0.01 ° SAE J1939 | Emitted interference | EN 61000-6-4 ISO 7637-2* CISPR 25:2008 (301000 MHz) |
| Accuracy (+25 °C) | Typ. ±0.1° | | * Severity level according to ECE R10 |
| Repeatability typ. | 0.025 ° (+25 °C) | | (Rev. 6 + Amd 02:2021-12) |
| Absolute accuracy max. (horizontal) | ±0.24° (+25°C) ±0.41° (0+50°C) (measuring range ±10°, see general in- formation) | MTTF _d (ISO 13849) | High (>100 years) Use in safety functions exclusively based on Application Note and MTTFd reliability prediction (request separately). |
| "Absolute accuracy max. (vertical) | ±0.47° (+25 °C) ±0.86° (0+50 °C) (measuring range ±10°, see general information) | Programmable parameters | Preset Zero position Signal low-pass filter Inverting of counting direction |
| Cross-axis-sensitivity max. | ±0.23° (2-dimensional horizontal) | Diagnostic function | Parameter error |
| (+25 °C) | ±0.47° (2-dimensional vertical) Measuring range ±10° | Technical data - mechanica | al design |
| Sensing method | MEMS technology | Dimensions W x H x L | 72 x 24 x 64 mm |
| Sensing metriod Sensing rate | 1000 Hz (1 ms) | Protection EN 60529 | IP 67 |
| Limit frequency | 0.125 Hz, 2. order / low-pass filter (De- | | IP 68 (without connector) IP 69K (without connector) |
| Limit requericy | fault: 5 Hz) | Material | Housing: polyamide (glass fiber rein- |
| Output stages | CAN-Bus compatible ISO 11898 | Matchai | forced) |
| Load dump protection | ISO 16750-2 for 12 V/24 V systems | | Base plate: metal |
| | Pulse 5b (test criteria A) | Corrosion protection | IEC 60068-2-52 Salt mist for ambient conditions CX (C5-M) accord- ing to ISO 12944-2 |
| | | Operating temperature | -40+85 °C (see general information) |

Inclination sensors

GIM600R - 2-dimensional

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| Technical data | | | | | | |
|--|------------------------------------|------------------------------------|---|--|--|--|
| Technical data - mechanical design | | Technical data - mechanical design | | | | |
| Resistance EN 60068-2-6 Vibration 20 g, 60-2000 l EN 60068-2-27 Shock 200 g, 3 ms | EN 60068-2-6 | Weight approx. | 150 g | | | |
| | | Connection | Flylead connector M12, 5-pin, length 300 mm | | | |
| Temperature changes | EN 60068-2-14, -40+85 °C, 5 cycles | | | | | |

Optional

3-axis acceleration PDO mappable (range ±2 g, see general information)



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General information

Self-heating correlated to installation and ambient conditions as well as to electronics and supply voltage must be considered for precise thermal dimensioning. The inclination sensor is supposed to self-heating to approximately 5 K when attached to a varnished ground metal. Operating the inclination sensor close to the maximum limits requires measuring the currently prevailing temperature at the housing. Electromagnetic interference can lead to reduced measuring accuracy (see application note). Sensor referencing to the zero position only in installed condition. Regularly verify the sensor's zero position upon stability when installed. Acceleration output values (optional) for information only. Further information on request.

Installation position



Horizontal installation

When installing the 2-dimensional inclination sensor with the housing in horizontal position, make sure the base plate is aligned parallel to the horizontal line.

The sensor can be inclined both arounds the X- and the Y-axis. There is one measured value supplied for each axis. Sensor default is 2-dimensional measuring within the selected range, e.g. ±30°. Zero-crossing is exactly in the horizontal line.









Y-axis 0°



Y-axis +30°





Vertical installation

When installing the 2-dimensional inclination sensor with the housing in vertical position, make sure the base plate is aligned parallel to the vertical line. The sensor can be inclined both around the X and the Z axis. There is one measured value supplied for each axis.

Sensor default is 2-dimensional measuring within the selected range, e.g. ±30°. Zero-crossing is exactly in the vertical line.

X-axis 0°



X-axis -30°



Z-axis 0°



Z-axis +30°



2024-05-29

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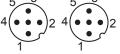
| Terminal assignment | | | | | | |
|----------------------|--------------|---|--|--|--|--|
| Cable with | connector M1 | 2, 5-pin | | | | |
| Pin | Assignment | Description | | | | |
| 1 | CAN_GND | Ground connection relating to CAN | | | | |
| 2 | +Vs | Voltage supply | | | | |
| 3 | GND | Ground connection relating to +Vs | | | | |
| 4 | CAN_H | CAN Bus Signal (dominant High) | | | | |
| 5 | CAN_L | CAN Bus Signal (dominant Low) | | | | |
| 5 3 4 • • • • • 2 | 2 | M12 flange connector (male), A-coded | | | | |

Cable with connector 2xM12, 5-pin (Bus-in/Bus-out)

| | | , |
|------------------|------------|--|
| Pin | Assignment | Description |
| 1 | CAN_GND | Ground connection relating to CAN |
| 2 | +Vs | Voltage supply |
| 3 | GND | Ground connection relating to +Vs |
| 4 | CAN_H | CAN Bus Signal (dominant High) |
| 5 | CAN_L | CAN Bus Signal (dominant Low) |
| 5 3 4 (• • •) | 3 5 | M12 flange connector (male / female), A-coded |

Cable with connector 2xM12, 5-pin (2x Bus-in)

| | | , - () |
|-----|------------|--------------------------------------|
| Pin | Assignment | Description |
| 1 | CAN_GND | Ground connection relating to CAN |
| 2 | +Vs | Voltage supply |
| 3 | GND | Ground connection relating to +Vs |
| 4 | CAN_H | CAN Bus Signal (dominant High) |
| 5 | CAN_L | CAN Bus Signal (dominant Low) |
| 5 3 | 5 3 | M12 flange connector (male), A-coded |



For all connection types

Terminals GND and CAN_GND are internally connected and identical in their functions. Max. load on the internal terminal connections Vs-Vs and GND-GND is 1.5 A each. Daisy chain current max. 1.5 A.

SAE J1939 features

Default Resolution 0.1°

Transmission rate 250 kbit/s

Address: 247, 248 (redundant version)

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| CANopen® features | |
|-------------------|---|
| Device profile | CANopen® CiA DSP 301 V4.2 Encoder profile DS 406 V4.0.2 Inclinometer profile DS 410 V1.3 LSS service profile DS 305 V2.2 |
| Default | Resolution 0.1° Baud rate 250 kbit/s Node-ID 1 Node-ID 2 (redundant version) Time-driven: 100 ms |

Data transfer

CANopen - PDO Mapping / Node-ID 1 / PDO 1

| LSB | MSB | LSB | MSB | LSB | MSB |
|-----------|-----|---|------------------------|---|------------------------|
| Byte 0 | 1 | 2 | 3 | 4 | 5 |
| Temperatu | | Inlination a X = 0 ▶ ±9 in steps of Angle incre size and va | 0° 0.1° asing in | Inlination a Y = 0 ▶ ±9 in steps of Angle incre size and va | 0° 0.1° asing in |

CANopen - PDO Mapping / Node-ID 2 / PDO 1

| LSB | MSB | LSB | MSB | LSB | MSB | | |
|-----------|-----|---|------------------------|---|-----|--|--|
| Byte 0 | 1 | 2 | 3 | 3 4 5 | | | |
| Temperatu | re | Inlination at X = 0 ▶ ±9 in steps of Angle incresize and va | 0° 0.1° asing in | Inlination angle Y = 0 ▶ ±90° in steps of 0.1° Angle increasing in size and value | | | |

SAE J1939 - PPGN 6563: 2-dimensional device message

Proprietary B message interpretation of 2-dimensional inclination sensors:

| LSB | MSB | LSB | MSB | LSB | MSB | LSB | MSB |
|-----------|------------------------------|-----------|---------|--------|-----|----------|-----|
| Byte 1 | 2 | 3 4 5 | | 5 | 6 | 7 | 8 |
| word tilt | igned reading on 0.1°) | word tilt | reading | signed | | Error ID | |

Data length: 8 bytes Extended data page: 0 Data page: 0

PF: 255 (Prop. B) PS: 83

PS: 83 Priority: 6

PG number: 65363 (00FF53h)

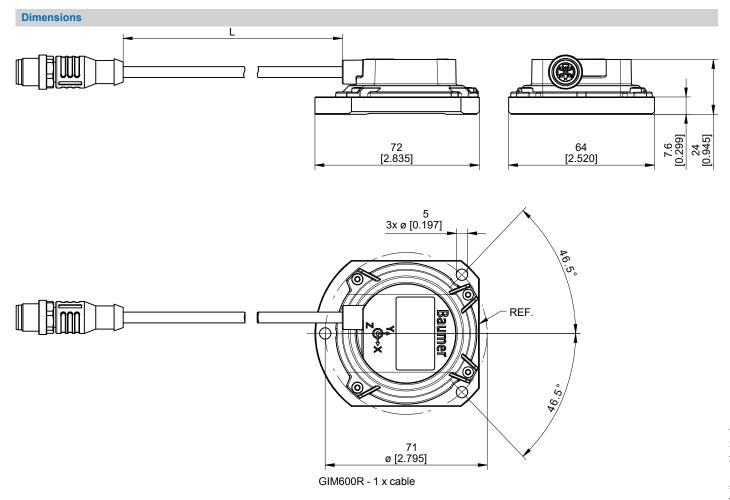
Description of data payload:

Byte 1: X-axis signed word LSB tilt reading (resolution 0.1°)
Byte 2: X-axis signed word MSB tilt reading (resolution 0.1°)
Byte 3: Y-axis signed word LSB tilt reading (resolution 0.1°)
Byte 4: Y-axis signed word MSB tilt reading (resolution 0.1°)
Byte 5: Device temperature signed byte (resolution 1 °C)

Byte 6: Module ID Byte 7,8: Error ID

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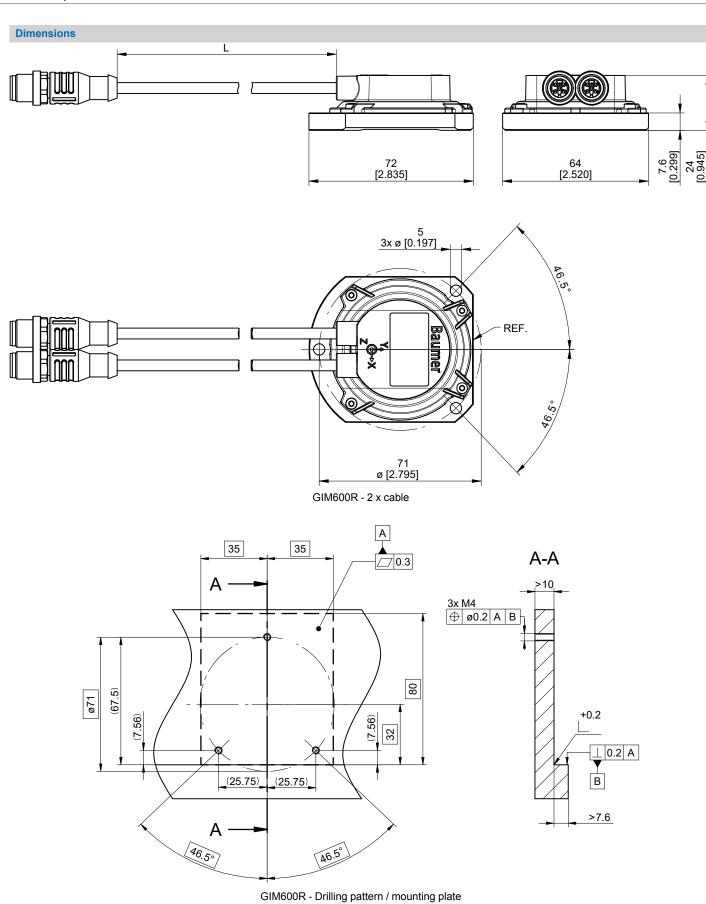
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| Ordering reference | | | | | | | |
|---|---------|-----|---|----|---|----|------------|
| | GIM600R | - N | # | 90 | # | ## | A / |
| Product | | | | | | | |
| | GIM600R | | | | | | |
| Housing | | | | | | | |
| Plastic reinforced / base plate metal | | N | | | | | |
| Number of axes | | | | | | | |
| 2-dimensional, housing horizontal | | | 2 | | | | |
| 2-dimensional, housing vertical ⁽²⁾ | | | ٧ | | | | |
| Measuring range | | | | | | | |
| ±90° | | | | 90 | | | |
| Connection ⁽¹⁾ | | | | | | | |
| Cable 0.3 m with M12, 5-pin, male contacts | | | | | S | | |
| 2x cable 0.3 m with M12, 5-pin, male and female contacts (Bus-in/out) | | | | | Р | | |
| 2x cable 0.3 m with M12, 5-pin, 2x male contacts (2x Bus-in) | | | | | R | | |
| Voltage supply / interface | | | | | | | |
| 836 VDC / CANopen® | | | | | | C6 | |
| 836 VDC / CANopen® (DS410) redundant (2-channel design) | | | | | | C8 | |
| 836 VDC / SAE J1939 | | | | | | C9 | |
| 836 VDC / SAE J1939 redundant (2-channel design) | | | | | | CR | |
| Operating temperature | | | | | | | |
| -40+85 °C | | | | | | | Α |
| | | | | | | | |

Option

Without option

- (1) Other connection types on request
- (2) On request